## Reasoning about Program Equivalence using (Prob)GKAT

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#### Joint work with ...

















### Motivation: comparing programs



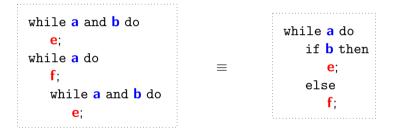


## Motivation: comparing programs





## A more complicated equivalence





#### Initial questions

- What is the minimal set of axioms?
- Are those axioms complete w.r.t. some model?
- Can we decide axiomatic equivalence?





$$\mathbf{a},\mathbf{b}::=t\in \mathcal{T}\mid \mathbf{a}+\mathbf{b}\mid \mathbf{ab}\mid \overline{\mathbf{a}}\mid 0\mid 1$$

$$\mathbf{e}, \mathbf{f} ::= \mathbf{a} \mid \mathbf{p} \in \Sigma \mid \mathbf{ef} \mid \mathbf{e} +_{\mathbf{a}} \mathbf{f} \mid \mathbf{e}^{(\mathbf{a})}$$



Treat while-programs as expressions — c.f. (Kozen and Tseng 2008).

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 $\mathbf{a} \text{ or } \mathbf{b}$ 

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 $\mathbf{e}; \mathbf{f}$ 



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e, f ::= a | 
$$p \in \Sigma$$
 | ef | e +<sub>a</sub> f | e<sup>(a)</sup>  
if a then e else f



$$\mathbf{a}, \mathbf{b} ::= t \in T \mid \mathbf{a} + \mathbf{b} \mid \mathbf{ab} \mid \overline{\mathbf{a}} \mid \mathbf{0} \mid \mathbf{1}$$

$$\mathbf{e},\mathbf{f}::=\mathbf{a}\mid p\in\Sigma\mid\mathbf{ef}\mid\mathbf{e}+_{\mathbf{a}}\mathbf{f}\mid\mathbf{e}^{(\mathbf{a})}$$
 while  $\mathbf{a}$  do  $\mathbf{e}$ 



 $\mathbf{e} +_{\mathbf{a}} \mathbf{e} \equiv \mathbf{e}$ 



 $\mathbf{e} +_{\mathbf{a}} \mathbf{e} \equiv \mathbf{e}$   $\mathbf{e} +_{\mathbf{a}} \mathbf{f} \equiv \mathbf{f} +_{\overline{\mathbf{a}}} \mathbf{e}$ 



$$e +_a e \equiv e$$
  $e +_a f \equiv f +_{\overline{a}} e$   $e +_a f \equiv ae +_a f$ 



$$\mathbf{e} +_{\mathbf{a}} \mathbf{e} \equiv \mathbf{e}$$
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if a then  ${\bf e}$  else assert false =  ${\bf e} +_{\bf a} {\bf 0}$ 



$$\mathbf{e} +_{\mathbf{a}} \mathbf{e} \equiv \mathbf{e}$$
  $\mathbf{e} +_{\mathbf{a}} \mathbf{f} \equiv \mathbf{f} +_{\overline{\mathbf{a}}} \mathbf{e}$   $\begin{vmatrix} \mathbf{e} +_{\mathbf{a}} \mathbf{f} \equiv \mathbf{a} \mathbf{e} +_{\mathbf{a}} \mathbf{f} \end{vmatrix}$   $\overline{\mathbf{a}} \mathbf{a} \equiv 0$   $0 \mathbf{e} \equiv 0$ 

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  $\mathbf{e} +_{\mathbf{a}} \mathbf{f} \equiv \mathbf{f} +_{\overline{\mathbf{a}}} \mathbf{e}$   $\mathbf{e} +_{\mathbf{a}} \mathbf{f} \equiv \mathbf{a} \mathbf{e} +_{\mathbf{a}} \mathbf{f}$   $\overline{\mathbf{a}} \mathbf{a} \equiv 0$   $0 \mathbf{e} \equiv 0$ 

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$$\equiv {\bf 0} +_{\overline{\bf a}} \, {\bf a} {\bf e}$$



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if a then e else assert false =  $e +_a 0 \equiv ae +_a 0$   $\equiv 0 +_{\overline{a}} ae$   $\equiv \overline{0}e +_{\overline{a}} ae$   $\equiv \overline{a}ae +_{\overline{a}} ae$  $\equiv ae +_{\overline{a}} ae$ 



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 $\equiv ae +_{\overline{a}} ae$   
 $\equiv ae = ae +_{\overline{a}} ae$ 



 $\mathbf{e} +_{\mathbf{a}} \mathbf{e} \equiv \mathbf{e} \qquad \mathbf{e} +_{\mathbf{a}} \mathbf{f} \equiv \mathbf{f} +_{\overline{\mathbf{a}}} \mathbf{e} \qquad (\mathbf{e} +_{\mathbf{a}} \mathbf{f}) +_{\mathbf{b}} \mathbf{g} \equiv \mathbf{e} +_{\mathbf{a}\mathbf{b}} (\mathbf{f} +_{\mathbf{b}} \mathbf{g})$  $\mathbf{e} +_{\mathbf{a}} \mathbf{f} \equiv \mathbf{a}\mathbf{e} +_{\mathbf{a}} \mathbf{f} \qquad \mathbf{e}\mathbf{g} +_{\mathbf{a}} \mathbf{f}\mathbf{g} \equiv (\mathbf{e} +_{\mathbf{a}} \mathbf{f})\mathbf{g} \qquad (\mathbf{e}\mathbf{f})\mathbf{g} \equiv \mathbf{e}(\mathbf{f}\mathbf{g}) \qquad \mathbf{0}\mathbf{e} \equiv \mathbf{0}$  $\mathbf{e}\mathbf{0} \equiv \mathbf{0} \qquad \mathbf{1}\mathbf{e} \equiv \mathbf{e} \qquad \mathbf{e}\mathbf{1} \equiv \mathbf{e} \qquad \mathbf{e}^{(\mathbf{a})} \equiv \mathbf{e}\mathbf{e}^{(\mathbf{a})} +_{\mathbf{a}}\mathbf{1} \qquad (\mathbf{e} +_{\mathbf{a}} \mathbf{1})^{(\mathbf{b})} \equiv (\mathbf{a}\mathbf{e})^{(\mathbf{b})}$ 



Fixpoints: If  $\mathbf{fe} +_{\mathbf{b}} \mathbf{g} \equiv \mathbf{e}$  and  $\mathbf{e}$  is productive, then  $\mathbf{f}^{(\mathbf{b})}\mathbf{g} \equiv \mathbf{e}$ .



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Unique solutions: affine systems of equations, i.e., of the form

.

have at most one solution (up to  $\equiv$ ) — provided the  $\mathbf{e}_{i,j}$  are *productive*.

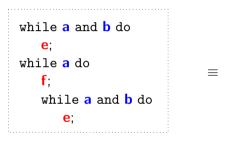


#### Theorem (Smolka et al. (2020))

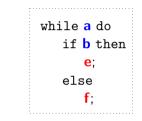
- $\blacktriangleright$  = is sound and complete w.r.t. a natural model.
- $\blacktriangleright$  = is decidable in nearly-linear time (for a fixed number of tests).



A more complicated equivalence



 $e^{(ab)} \cdot (fe^{(ab)})^{(a)}$ 



 $(\mathbf{e} +_{\mathbf{b}} \mathbf{f})^{(\mathbf{a})}$ 



#### Followup questions

- What if we drop the axiom  $e0 \equiv 0$ ?
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Third question remains open!



#### Intuition: "failing now is the same as failing later" ....



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... but what if the actions before failure matter?



Provable in GKAT:  $e^{(a)} \equiv e^{(a)}\overline{a}$ .



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See also (Mamouras 2017).



### Mission statement

#### Question

Let  $\equiv_0$  be like  $\equiv$ , but without relating **e**0 to 0.

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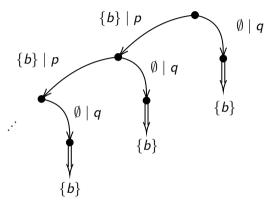
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Roadmap:

- 1. Find a model satisfying the axioms.
- 2. Prove soundness and completeness.
- 3. Decide equivalence within that model.

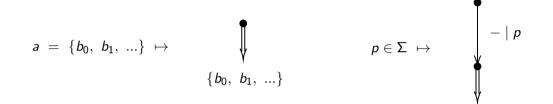


## Guarded trees — example



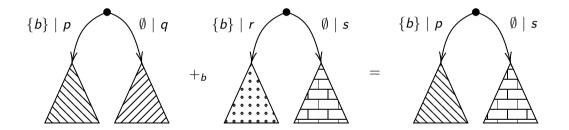


Expressions to trees — base case



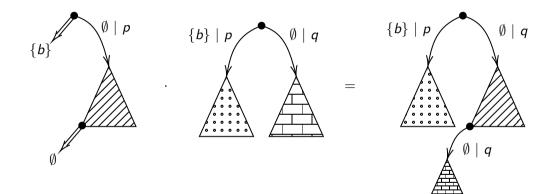


## Expressions to trees — Party hat diagrams



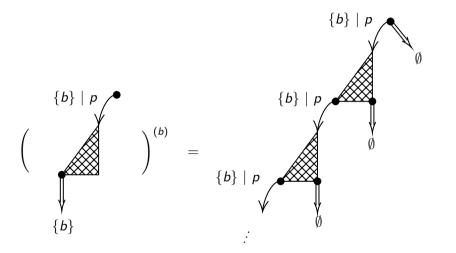


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Question (Decidability) Can we decide whether [e] = [f]?



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Corollary (Decidability for terms) It is decidable whether  $\mathbf{e} \equiv_0 \mathbf{f}$ 

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The "old" results from (Smolka et al. 2020) can be recovered from these.



#### Question

Let t be a guarded tree with finitely many distinct subtrees.

Is there an **e** such that  $\llbracket \mathbf{e} \rrbracket = t$ ?

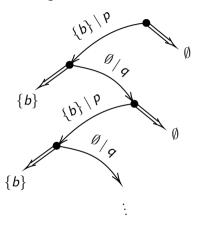


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See also (Kozen and Tseng 2008).



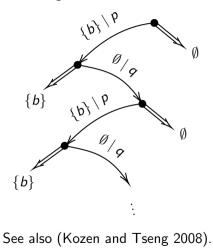
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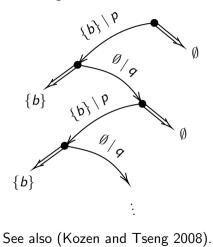
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 $\ell_0:$  if **b** then p; goto  $\ell_1$  else accept  $\ell_1:$  if  $\overline{\mathbf{b}}$  then q; goto  $\ell_0$  else accept

Not in general — for instance:



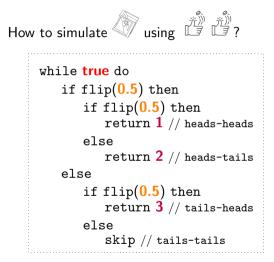


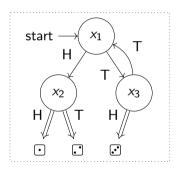
## Knuth-Yao algorithm





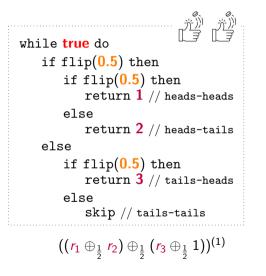
# Knuth-Yao algorithm







# Correctness of Knuth-Yao in ProbGKAT



if flip(1/3) then return 1
else if flip( <mark>0.5</mark> ) then
return 2
else
return 3
$r_1\oplus_{\frac{1}{3}}(r_2\oplus_{\frac{1}{2}}r_3)$

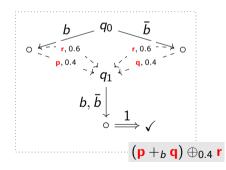
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### Operational model

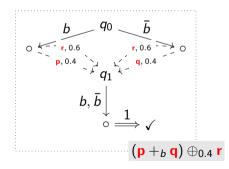
Automata with the transition function of the type  $Q imes \mathtt{At} o \mathcal{D}_\omega(\{\checkmark, X\} + V + \mathtt{Act} imes Q)$ 





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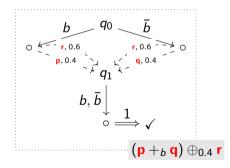


Notion of equivalence: bisimulation associated with the type functor



## Operational model

Automata with the transition function of the type  $Q imes \mathtt{At} o \mathcal{D}_\omega(\{\checkmark, X\} + V + \mathtt{Act} imes Q)$ 



- Notion of equivalence: bisimulation associated with the type functor
- Can be decided in O(n<sup>2</sup> log(n)) using a generic minimization algorithm (Wißmann et al, 2020)



## Overview

- GKAT describes general equivalences of programs.
- It admits a complete axiomatization and is decidable.
- There is a model for the theory without  $e0 \equiv 0$ .
- Soundness and completeness can be recovered.
- Lack of GOTO means not every tree is expressible.
- A probabilistic extension is in the works.

https://kap.pe/slides https://kap.pe/papers



Nearly-linear complexity is  $O(\alpha(n) \cdot n)$ , where  $\alpha$  is the *inverse Ackermann function*.

Fun fact:  $\alpha(n) \leq 5$  for most numbers you can think of:

- Grains of sand in the Sahara.
- ► The number of DNA base pairs on earth.
- Number of protons in the observable universe.

See also (Tarjan 1975).



Syntax is special case of Kleene Algebra with Tests (KAT):

```
if a then e else f end \mapsto \mathbf{a} \cdot \mathbf{e} + \overline{\mathbf{a}} \cdot \mathbf{f}
```

while **a** do **e** end  $\mapsto$   $(\mathbf{a} \cdot \mathbf{e})^* \cdot \overline{\mathbf{a}}$ 



Syntax is special case of Kleene Algebra with Tests (KAT):

```
if a then e else f end \mapsto a \cdot e + \overline{a} \cdot f
```

while **a** do **e** end  $\mapsto$   $(\mathbf{a} \cdot \mathbf{e})^* \cdot \overline{\mathbf{a}}$ 

Known results:

- ▶ There is a "nice" set of axioms for KAT.
- Soundness & completeness for a straightforward model.
- Equivalence according to these axioms is decidable.

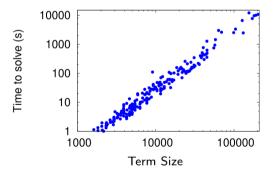


Equivalence in KAT is PSPACE-complete (Cohen, Kozen, and Smith 1996).



Equivalence in KAT is PSPACE-complete (Cohen, Kozen, and Smith 1996).

But for practical inputs, good algorithms scale well — e.g., (Foster et al. 2015):





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